

DYNAMAX



Staubli Robots

Robotic Spindle Matrix

Dynamax Spindle

	RX130L	RX130XL	RX60	RX90	TX90XL	TX90L	TX90	RX130	RX170L	RX170	RX170HP	RX260	RX270L
06-2A-BM-1.4-1091	•	•	•	•	•	•	•	•	•	•	•	•	•
06-2A-BM-1.4-1092	•	•	•	•	•	•	•	•	•	•	•	•	•
06-2A-FM-1.4-1090	-	-	-	-	-	-	-	-	-	-	-	-	-
09-2C-C-8.0-1190	-	-	-	-	-	-	-	-	-	-	-	-	-
09-2C-C-8.0-1192	-	-	-	-	-	-	-	-	-	-	-	-	-
10-2A-C-8.0-0980	-	-	-	-	-	-	-	-	-	-	-	-	-
10-2A-C-8.0-0981	-	-	-	-	-	-	-	-	-	-	-	-	-
04-2C-BM-2.0-0565	-	-	-	-	-	-	-	-	-	-	-	-	-
04-2C-BM-2.0-0566	-	-	-	-	-	-	-	-	-	-	-	-	-
07-2A-BM-2.0-0561	-	-	-	-	-	-	-	-	-	-	-	-	-
07-2A-BM-2.0-0564	-	-	-	-	-	-	-	-	-	-	-	-	-
09-2C-C-8.0-1191	-	-	-	-	-	-	-	-	-	-	-	-	-
07-2A-BM-2.0-0563	-	-	-	-	-	-	-	-	-	-	-	-	-
07-2A-BM-2.0-0610	-	-	-	-	-	-	-	-	-	-	-	-	-
04-2C-BM-2.0-0568	-	-	-	-	-	-	-	-	-	-	-	-	-
07-2A-BM-2.0-0562	-	-	-	-	-	-	-	-	-	-	-	-	-
07-2A-BM-2.0-0560	-	-	-	-	-	-	-	-	-	-	-	-	-
07-2A-BM-2.0-0612	-	-	-	-	-	-	-	-	-	-	-	-	-
07-2A-BM-2.0-0611	-	-	-	-	-	-	-	-	-	-	-	-	-
13-3C-FM-11-HSE070B-MA	-	-	-	-	-	-	-	-	-	-	-	-	-
13-3C-FM-15-HSE070C-MA	-	-	-	-	-	-	-	-	-	-	-	-	-
07-2A-BM-2.0-0613	-	-	-	-	-	-	-	-	-	-	-	-	-
11-3A-FM-15-HSE070D-MA	-	-	-	-	-	-	-	-	-	-	-	-	-
13-3A-FM-13-HSE090B-MA	-	-	-	-	-	-	-	-	-	-	-	-	-
13-3A-FM-18-HSE090C-MA	-	-	-	-	-	-	-	-	-	-	-	-	-
13-3A-FM-24-HSE090D-MA	-	-	-	-	-	-	-	-	-	-	-	-	-
11-3A-FM-11-HSE070B-AA	-	-	-	-	-	-	-	-	-	-	-	-	-
11-3A-FM-15-HSE070C-AA	-	-	-	-	-	-	-	-	-	-	-	-	-
13-3C-FM-11-HSE070B-MS	-	-	-	-	-	-	-	-	-	-	-	-	-
13-3C-FM-15-HSE070D-AA	-	-	-	-	-	-	-	-	-	-	-	-	-
11-2C-C-3.0-0500	-	-	-	-	-	-	-	-	-	-	-	-	-
11-2C-C-3.0-0501	-	-	-	-	-	-	-	-	-	-	-	-	-
13-3C-FM-15-HSE070C-MS	-	-	-	-	-	-	-	-	-	-	-	-	-
13-3A-FM-13-HSE090B-AA	-	-	-	-	-	-	-	-	-	-	-	-	-
13-3A-FM-18-HSE090C-AA	-	-	-	-	-	-	-	-	-	-	-	-	-
11-3A-FM-15-HSE070D-MS	-	-	-	-	-	-	-	-	-	-	-	-	-
13-3A-FM-24-HSE090D-AA	-	-	-	-	-	-	-	-	-	-	-	-	-
13-3A-FM-13-HSE090B-MS	-	-	-	-	-	-	-	-	-	-	-	-	-
13-3A-FM-18-HSE090C-MS	-	-	-	-	-	-	-	-	-	-	-	-	-
11-3A-FM-11-HSE070B-AS	-	-	-	-	-	-	-	-	-	-	-	-	-
11-3A-FM-15-HSE070C-AS	-	-	-	-	-	-	-	-	-	-	-	-	-
13-3A-FM-24-HSE090D-MS	-	-	-	-	-	-	-	-	-	-	-	-	-
18-3A-FM-7.5-1270	-	-	-	-	-	-	-	-	-	-	-	-	-
13-3C-FM-15-HSE070D-AS	-	-	-	-	-	-	-	-	-	-	-	-	-
13-3A-FM-13-HSE090B-AS	-	-	-	-	-	-	-	-	-	-	-	-	-
13-3A-FM-18-HSE090C-AS	-	-	-	-	-	-	-	-	-	-	-	-	-
13-3A-FM-24-HSE090D-AS	-	-	-	-	-	-	-	-	-	-	-	-	-
13-3C-C-15-HSM100C-M	-	-	-	-	-	-	-	-	-	-	-	-	-
14-3C-C-13.5-HSM112A-M	-	-	-	-	-	-	-	-	-	-	-	-	-
13-3A-FM-16-HSE112A-MA	-	-	-	-	-	-	-	-	-	-	-	-	-
14-3C-C-20-HSM112B-M	-	-	-	-	-	-	-	-	-	-	-	-	-
13-3C-C-15-HSM100C-A	-	-	-	-	-	-	-	-	-	-	-	-	-
13-3A-FM-24-HSE112B-MA	-	-	-	-	-	-	-	-	-	-	-	-	-
14-3C-C-13.5-HSM112A-A	-	-	-	-	-	-	-	-	-	-	-	-	-
13-3A-FM-16-HSE112A-AA	-	-	-	-	-	-	-	-	-	-	-	-	-
12-3A-FM-10-0428	-	-	-	-	-	-	-	-	-	-	-	-	-
12-3A-FM-17-0660	-	-	-	-	-	-	-	-	-	-	-	-	-
14-3C-C-20-HSM112B-A	-	-	-	-	-	-	-	-	-	-	-	-	-
14-3C-C-27-HSM112C-M	-	-	-	-	-	-	-	-	-	-	-	-	-
14-3C-C-37.5-HSM112C-M	-	-	-	-	-	-	-	-	-	-	-	-	-
14-2A-C-1370	-	-	-	-	-	-	-	-	-	-	-	-	-
13-3A-FM-24-HSE112B-AA	-	-	-	-	-	-	-	-	-	-	-	-	-
14-3C-C-27-HSM112C-A	-	-	-	-	-	-	-	-	-	-	-	-	-
13-3A-FM-16-HSE112A-MS	-	-	-	-	-	-	-	-	-	-	-	-	-
14-3C-C-37.5-HSM112C-A	-	-	-	-	-	-	-	-	-	-	-	-	-
13-3A-FM-16-HSE112A-AS	-	-	-	-	-	-	-	-	-	-	-	-	-
13-3A-FM-24-HSE112B-MS	-	-	-	-	-	-	-	-	-	-	-	-	-
13-3A-FM-24-HSE112B-AS	-	-	-	-	-	-	-	-	-	-	-	-	-

Matrix created solely on basis of robot payload.
Application determination approved on a case by case basis.

Key: o Spindle mass acceptable for robot payload
- Spindle mass not acceptable for robot payload